

2013/12/09 NAFEMS Japan Conference

Development of User-Subroutines for Constitutive law by the cooperation of Industrial users, Software vendors and Academic researchers

JANCAE - Japan Association of NonLinear CAE

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Activities of NPO JANCAE

JANCAE.org

最新情報

- 2013/3/11
第23期非線形CAE勉強会のページを作成しました。
- 2013/1/15
ホームページをリニューアルいたしました。
- 2012/9/20
第23期非線形CAE勉強会の申し込みが完了しました。

第23期非線形CAE勉強会のお知らせ

- 基礎勉強会：2013年5月17日（金）
◎東海大学高輪キャンパス 2号館 2201+2202教室
- 1, 2日目：2013年5月18・19日（土・日）
◎東海大学高輪キャンパス 大講義室
- 3, 4日目：2013年6月1・2日（土・日）
◎中央大学駿河台記念館

◎ [詳細はこちら](#)

2012年度 第3回材料モデリング分科会のお知らせ

- 日時：2013年3月14日（木）10時～17時
- 会場：[中央大学駿河台記念館](#) 330教室

◎ [詳細はこちら](#)

「非線形有限要素法 弾塑性解析の理論と実践」
◎EA de Souza Neto D Peric DRJ Owen／原著 寺田賢二郎／監訳
◎森北出版株式会社
定価15000円＋税

◆ President : Prof. Kenjiro Terada (Tohoku Univ)

◆ Holding CAE training courses 2times/year as opportunities for companies, universities and software vendors to learn non-linear CAE

◆ Industrial companies usually use commercial CAE codes, and the deeper understanding is necessary for effective use of CAE

Activities of NPO JANCAE

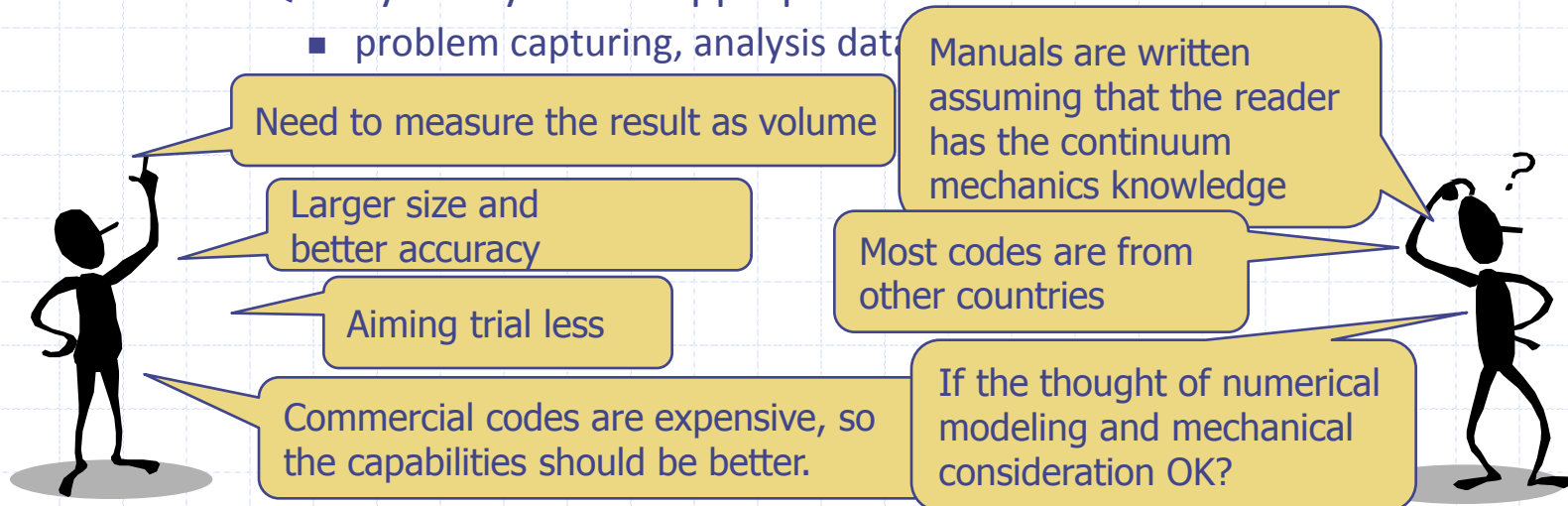
- ◆ Nonlinear CAE training courses: 24 times for the past 12 years
 - The number of participants
 - ◆ 200 in Tokyo, 2 weekends in May and June
 - ◆ 120 in Nagoya, 2 weekends in November and December
 - The participants
 - ◆ Industrial engineers of 30's and 40's (They pay the fee by themselves, not by companies)
 - ◆ Vendors engineers and academic related

Why 200 engineers gather for 2 weekends!?



Activities of NPO JANCAE

- ◆ Position in companies: CAE as “volume (Quantity)”
 - If using CAE...(*)... maybe the cost for prototype test will be decreased.
 - ◆ If improving analysis accuracy, “trial-less” design and manufacturing will be possible.
 - ◆ There are things between lines(*)
- ◆ Personal engineer: CAE as “Quality”
 - As valued by working volume, they need to deal with calculations
 - ◆ Volume: the number of analysis case, analysis accuracy, the number of license, the rate of operation...
 - Free-floating anxiety about “Quality”
 - ◆ Quality: Is my model appropriate ?
 - problem capturing, analysis data



Activities of NPO JANCAE

◆ Participants needs

- Vendors seminars: Usually how to use the commercial software codes
 - ◆ Valid for beginners, but not involved deeply in the real problems.
 - ◆ Discussion is about specific software: How To Use/Push Button.
- Universities/Academic societies: Basic theory and result of leading research
 - ◆ General basic theory: Already embedded in commercial codes
 - ◆ Leading research result: Can't use with a little study

◆ How to use knowledge we have learned?

◆ 3 Non Linearity

- Geometric NL
 - ◆ Theoretically completed. Difficult to be involved as users
- NL on Boundary condition
 - ◆ Related to core of the codes. Difficult to be involved as users
- Material NL
 - ◆ An enormous amount of material model, material test method
Parameter identification
 - ◆ Both vendors and users don't want to be involved?

Learn correctly

Model parameter
and verification

Learn in proper
order

Activities of NPO JANCAE

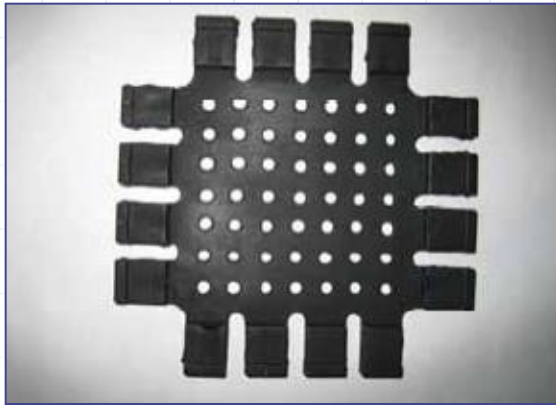
- ◆ Material modeling committee (Rubber committee)
 - Small group (30~60)
 - Specific topics for deeper understanding and effectiveness in practical aspect

When we think of comprehensive advancements in the accuracy of a simulation, we are aware that all capabilities of the material modeling, the boundary conditions as well as the definition of the geometric modeling have to be improved at the same level. The capabilities of geometric modeling for FEM simulations have drastically improved along with the growth of the 3D CAD market, the advancements in auto-meshing capabilities and the progresses made in hardware speeds and capacities, over the past 10 years. Yet material modeling capabilities have not progressed as significantly as the advances achieved in geometric modeling. Users need to be involved in the definition process of material modeling, which means that they have to choose the appropriate material model from huge amounts of available material models offered by each FEM code. As a next step, the parameters of the material properties have to be determined by performing material tests. These processes are still necessary, even now, at a time when many sophisticated commercial FEM codes are available.

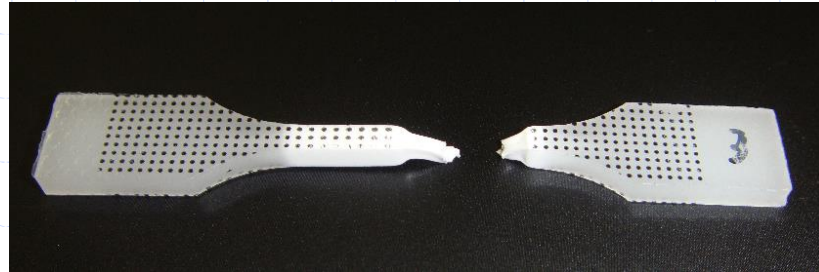
In this situation and independently from its CAE training course, which mainly consists of classroom lectures, JANCAE organizes “The Material Modeling Committee” as a practical approach to the study of nonlinear materials. The Committee was originally established in 2005 to study mainly hyperelasticity and viscoelasticity. Then, its research activities have diversified into all material nonlinearity including metal plasticity. In the frame of the Committee, members learn about typical nonlinear material modeling by studying the basic theory of the constitutive equations, material testing methods, and how to handle test data and parameter identification techniques.

Activities of NPO JANCAE

- ◆ Activities of material modeling committee
 - Collaboration and data sharing for nonlinear material test
 - ◆ Opened to the public
 - Training course for theory of constitutive law
 - ◆ Elastic ▪ HyperElastic ▪ ViscoElastic ▪ Plastic ▪ Creep...
 - ◆ Constitutive law developed in different fields (Metallurgy/Chemical/Process)



Rubber biaxial tensile test piece



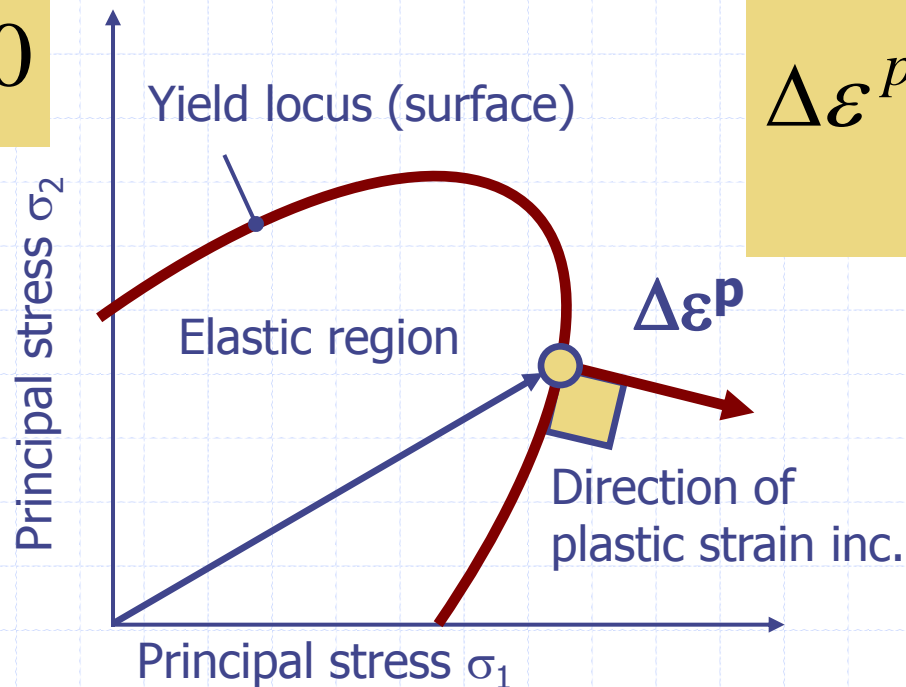
High speed uni-axial tensile test of polymer resin

- Activities to practically use what we learned practically

Basic for plastic theory

- ◆ Keyword to understand the theory of plasticity
 - Yield surface/Yield function
 - ◆ Assuming the function of stress components describing a surface in which the material is elastic, and on which plastic.
 - Normality rule : Condition of stable plastic deformation
 - ◆ Direction of plastic strain increment is same as normal on the yield surface

$$\sigma_e(\sigma_{ij}) = 0$$



$$\Delta \varepsilon^p = \Delta p \frac{\partial \sigma_e}{\partial \sigma_{ij}}$$

Commercial CAE codes:

◆ LS-DYNA(v972)

- TYPE 3,12,24 : vonMises
- TYPE 33,36 : Barlat(1991), Barlat(1996)
- TYPE 36 : Barlat(1989)
- TYPE 37,39,103,122 : Hill(1948)
- TYPE 133 : Barlat(2000)

◆ MSC.Marc(2008)

- VON MISES : von Mises
- HILL : Hill(1948)
- BARLAT : Barlat(1991)

◆ Abaqus(6.8), Adina, Ansys(11)

- von Mises
- Hill(1948)

Many anisotropic yield functions are prepared in LS-DYNA which focus on sheet metal forming as explicit method. However, implicit codes only have classical anisotropic yield functions.

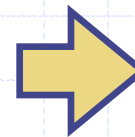
◆ User defined material model

- Commercial codes provide user sub routine for material model

◆ Self-study has a limit (too difficult to learn alone !)

- Backward Euler stress integration
- Consistent tangent coefficient
- Code dependent manner

◆ Both require lots of effort to users



Big gap between academic and industrial use

Basic theory of elasto-plastic constitutive law

- ◆ Basic formula (Isotropic hardening)
 - Voigt notation is used to fit to the user subroutine

Additive Decomposition

$$\{\Delta\varepsilon\} = \{\Delta\varepsilon^p\} + \{\Delta\varepsilon^e\}$$

$\sigma_e(\sigma)$: Yield Function

$\sigma_Y(p)$: Hardening Curve

Hooke's law

$$\{\Delta\sigma\} = [D^e]\{\Delta\varepsilon^e\}$$

Normality rule

$$\{\Delta\varepsilon^p\} = \Delta p \frac{\partial \sigma_e}{\partial \{\sigma\}} = \Delta p \frac{\partial \sigma_e}{\partial \{\sigma_{n+1}\}} \quad \text{Backward Euler}$$

Yield criterion

$$\sigma_e(\sigma_{n+1}) - \sigma_Y(p_{n+1}) = \sigma_e(\sigma_{n+1}) - \sigma_Y(p_n + \Delta p) = 0$$

Backward Euler

Elastic predictor – Plastic Corrector

$$\{\Delta\sigma\} = [D^e]\{\{\Delta\varepsilon\} - \{\Delta\varepsilon^p\}\} = [D^e]\{\Delta\varepsilon\} - [D^e]\Delta p \frac{\partial \sigma_e}{\partial \{\sigma_{n+1}\}}$$

$$\{\sigma_{n+1}\} = \{\sigma_n\} + \{\Delta\sigma\} = \underbrace{\{\sigma_n\} + [D^e]\{\Delta\varepsilon\}}_{\text{Trial stress } \{\sigma^{Try}\}} - [D^e]\Delta p \frac{\partial \sigma_e}{\partial \{\sigma_{n+1}\}}$$

Trial stress $\{\sigma^{Try}\}$

Elasto-plastic model: Stress integration

- ◆ Plandtl-Reuß (Analytical form)
 - L.Plandtl (1924)
 - E.Reuss (1930)

- ◆ Forward Euler (Tangential Predictor/r-min method)
 - P.V.Marcial, I.P.King (1967)
 - Y.Yamada(1967)
 - Y.Yamada, N.Yoshimura, T.Sakurai (1968)

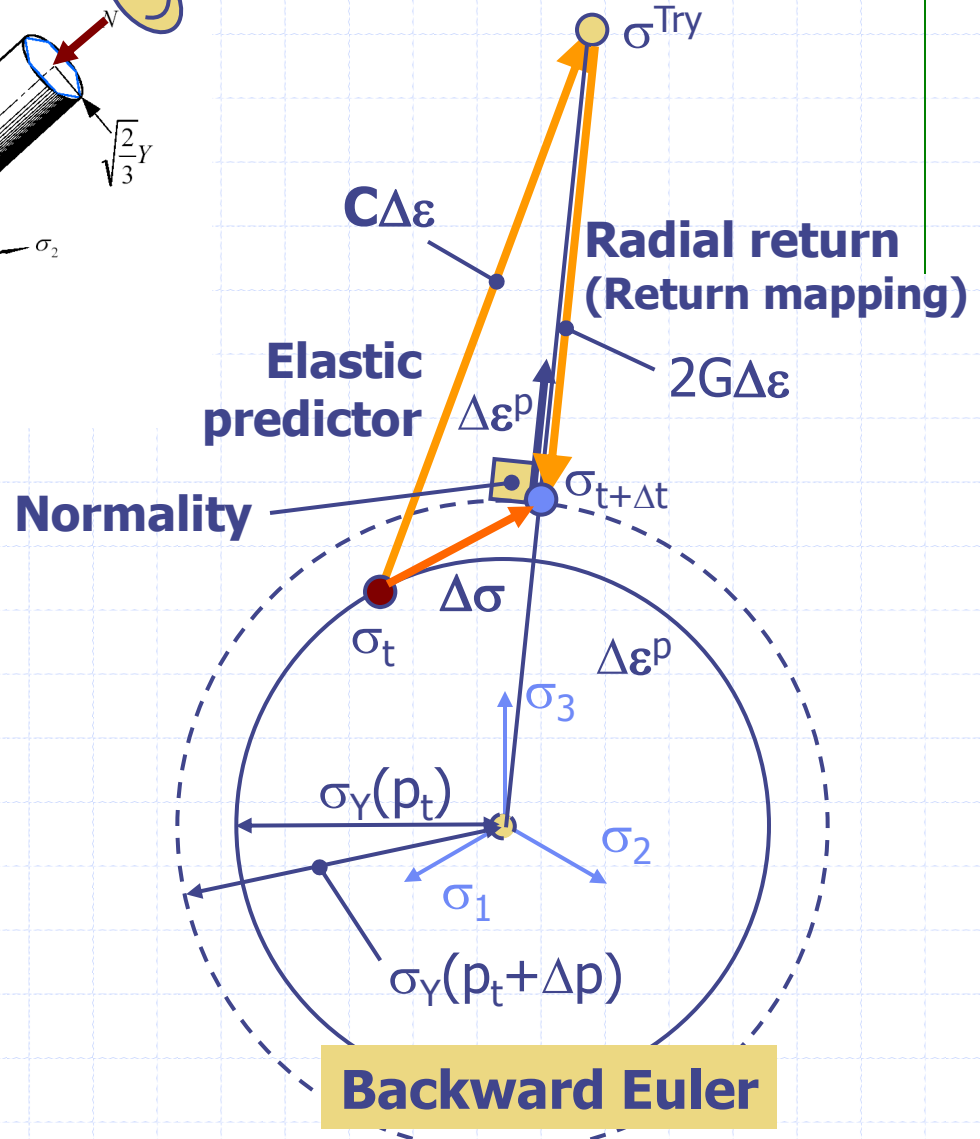
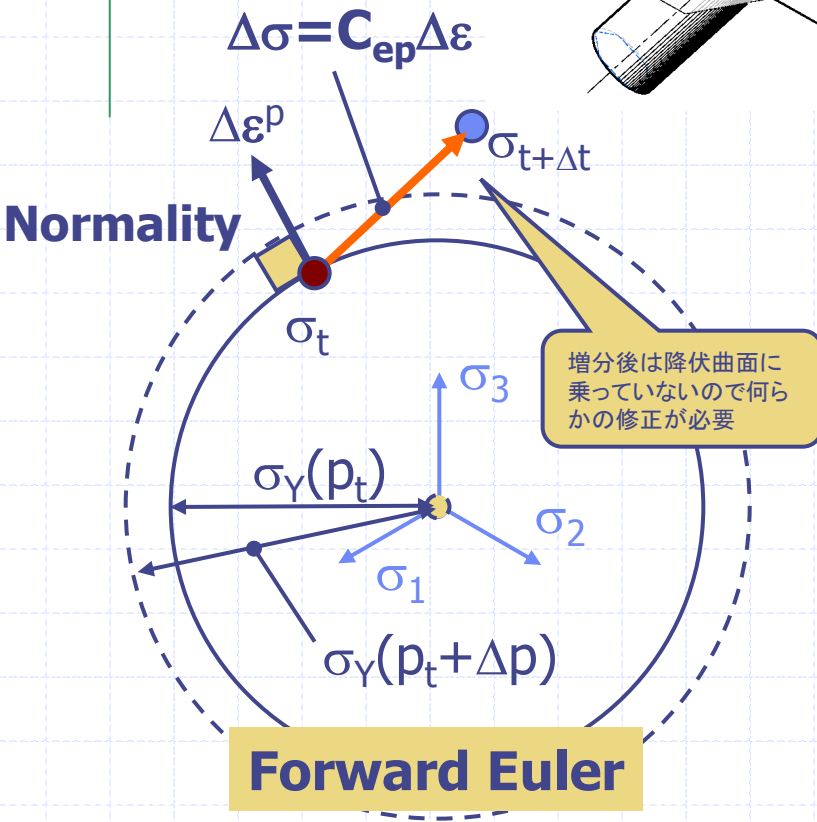
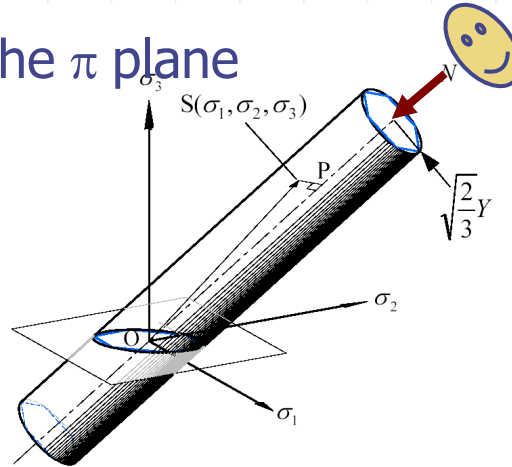
- ◆ Mean Normal Method
 - J.C.Nagtegaal, J.E.De Jong (1980,1981)
 - I.Pillinger, P.Hartley, C.E.N.Sturgess, G.W.Rowe (1986)

- ◆ Backward Euler (Elastic predictor-Return Mapping)
 - R.D.Krieg, D.B.Krieg (1977)
 - J.C.Nagtegaal (1982)
 - J.C.Simo, M.Ortiz (1985) : (Consistent Tangent)

- ◆ Multistage Return Mapping
 - ◆ M.Ortiz, J.C.Simo (1989)

Forward/Backward Euler

◆ Description on the π plane



Basic theory

Update of stress

$\delta\Delta p$ (Perturbation amount of Δp)

$$\delta\Delta p = g_1(\Delta p_{(i)}) - \frac{\partial \sigma_e}{\partial \{\sigma_{(i)}\}^T} [E]^{-1} \{g_2(\Delta p_{(i)})\}$$

$$\frac{\partial \sigma_e}{\partial \{\sigma_{(i)}\}^T} [E]^{-1} [D^e] \frac{\partial \sigma_e}{\partial \{\sigma_{(i)}\}} + \frac{d\sigma_Y}{dp_{(i)}}$$

$$[E] \equiv \left[[I] + \Delta p_{(i)} [D^e] \frac{\partial^2 \sigma_e}{\partial \{\sigma_{(i)}\} \partial \{\sigma_{(i)}\}^T} \right]$$

$\delta\sigma$ (Perturbation amount of σ)

$$\{\delta\sigma\} = -[E]^{-1} \left\{ \{g_2(\Delta p_{(i)})\} - [D^e] \delta\Delta p \frac{\partial \sigma_e}{\partial \{\sigma_{(i)}\}} \right\}$$

Update

$$\Delta p_{(i+1)} = \Delta p_{(i)} + \delta\Delta p$$

$$\{\sigma_{(i+1)}\} = \{\sigma_{(i)}\} + \{\delta\sigma\}$$

Check residuals

$$g_1(\Delta p_{(i+1)}) = \sigma_e(\sigma_{(i+1)}) - \sigma_Y(p_n + \Delta p_{(i+1)})$$

$$\{g_2(\Delta p_{(i+1)})\} = \{\sigma_{(i+1)}\} - \{\sigma^{Try}\} + \Delta p_{(i+1)} [D^e] \frac{\partial \sigma_e}{\partial \{\sigma_{(i+1)}\}}$$

σ_e and its differential

σ_Y and its differential

Convergence condition

$$g_1, \text{norm}\{g_2\} < \text{Tol}$$

NR
loop

Basic theory

◆ Consistent tangent modulus

$$\{\delta\sigma\} = [e]^{-1} \left[\begin{array}{c} [e]^{-1} \frac{\partial \sigma_e}{\partial \{\sigma_{n+1}\}} \otimes [e]^{-1} \frac{\partial \sigma_e}{\partial \{\sigma_{n+1}\}} \\ \frac{\partial \sigma_e}{\partial \{\sigma_{n+1}\}} [e]^{-1} \frac{\partial \sigma_e}{\partial \{\sigma_{n+1}\}} + \frac{d\sigma_Y}{dp_{n+1}} \end{array} \right] \{\delta\varepsilon\}$$

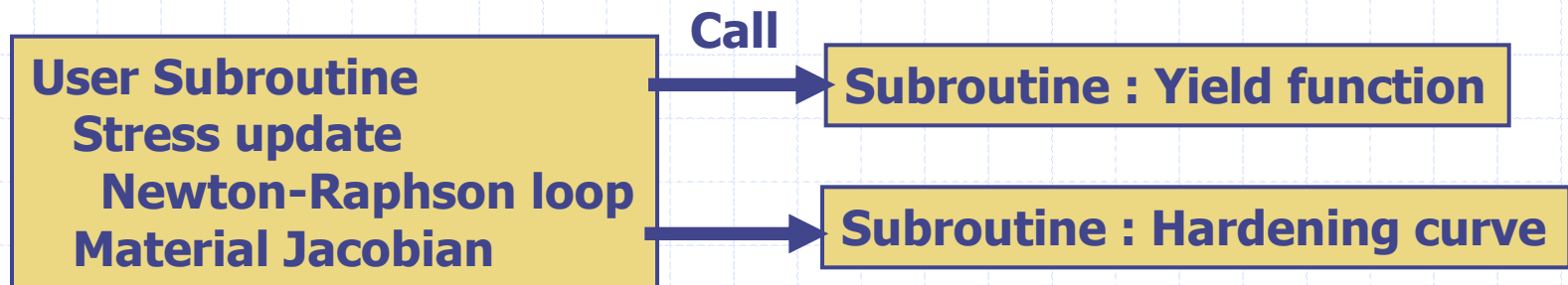
$$[e] = \left[[D^e]^{-1} + \Delta p \frac{\partial^2 \sigma_e}{\partial \{\sigma_{n+1}\} \partial \{\sigma_{n+1}\}^T} \right]$$

σ_e and its differential

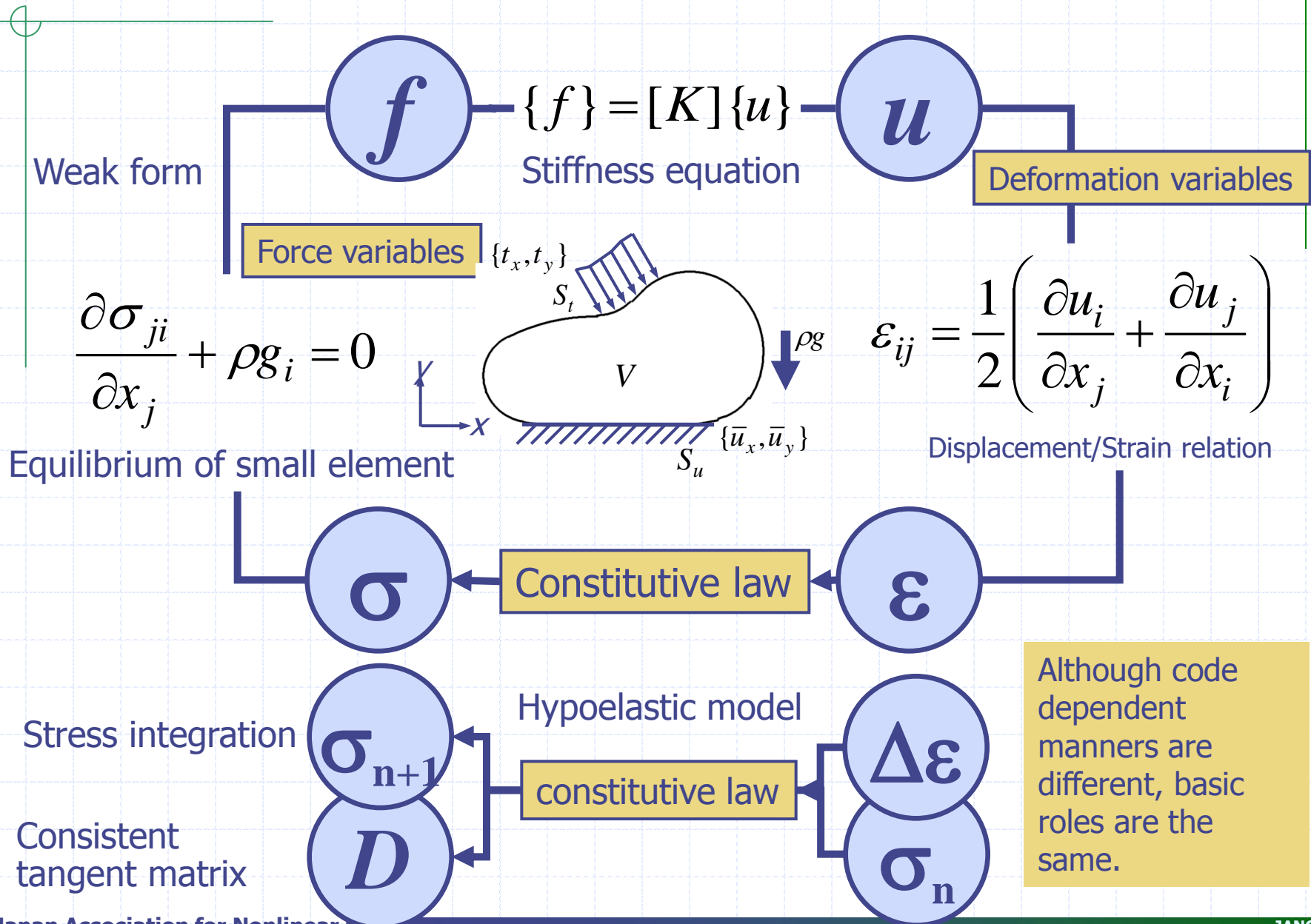
σ_y and its differential

Generalization of plastic constitutive law

- ◆ Given yield function (equivalent stress) and strain hardening law
 - For the given stress $\{\sigma\}$
 - ◆ Equivalent stress σ_e
 - ◆ First order differential by stress of equivalent stress $\partial\sigma_e / \partial\{\sigma\}$
 - ◆ Second order differential by stress of equivalent stress $\partial^2\sigma_e / \partial\{\sigma\}\partial\{\sigma\}^T$
 - And the given equivalent plastic strain p
 - ◆ Deformation resistance σ_Y
 - ◆ First order differential by p of deformation resistance $d\sigma_Y / dp$
 - Should to be returned.



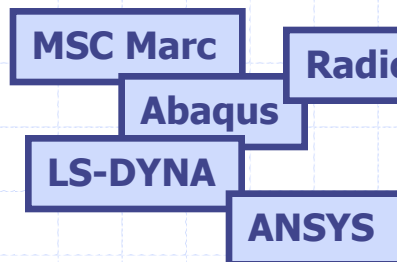
Role of constitutive law sub routine



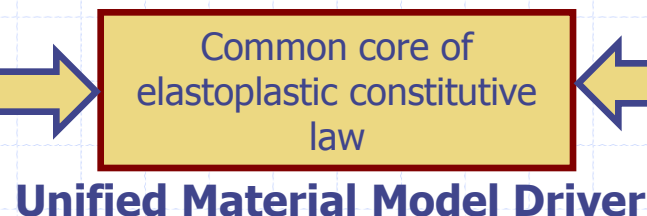
Externality of 2 kinds of diversity

- ◆ Diversity of commercial codes
 - User subroutine of commercial codes has different specifications.
 - ◆ User subroutine is discussed in the users meetings and seminars held by vendors.
 - However, role of constitutive law is common in continuum mechanics.
 - ◆ MSC Marc and Abaqus have the same manner to store array
- ◆ Diversity of yield functions
 - There are many proposals of yield functions from many researchers.
 - However, numerically, $\sigma_e(\sigma)$ and its differential are necessary for expression of yield function in codes.
 - ◆ Can be extended if being module by subroutine
 - Same for hardening law and hardening curve

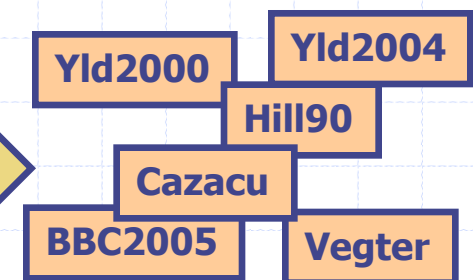
share development



Learn together



share development



The aim of the working group

◆ Understand

- Industrial companies tend to have tools that we can use easily for the short term benefit. But it is difficult to get a good result depend on understanding by using black box tool.
 - ◆ Constitutive law's role is independent from codes
 - ◆ So we can learn together

◆ Create

- Gaining peers understanding by setting clear target "user subroutine and peripheral programs"
 - ◆ Creating subroutine group which can be embedded in commercial codes
 - ◆ By doing so, creating basic technology for higher analysis

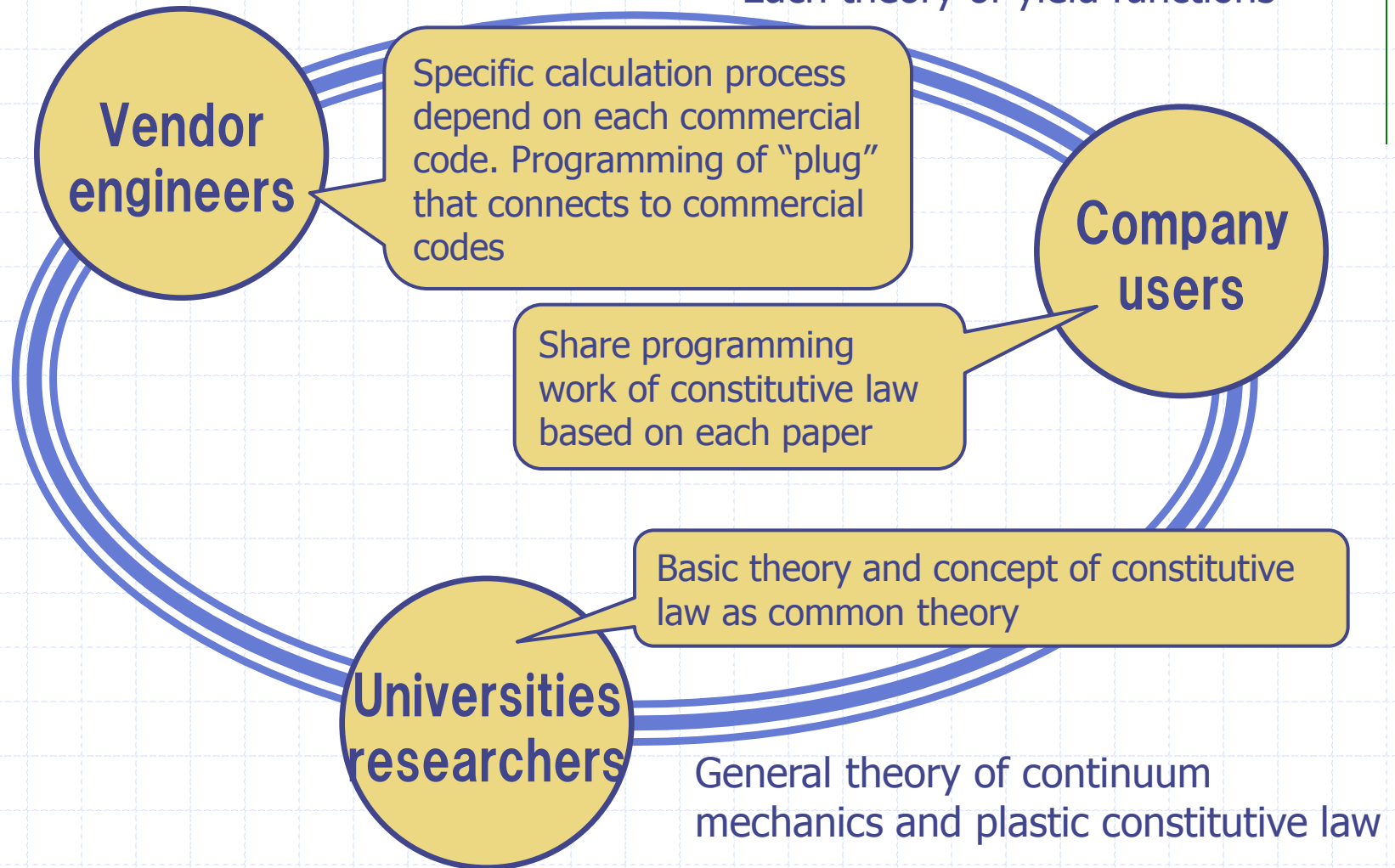
◆ Deliver

- Deliver the result so that successive engineers can follow the same process and much more engineers can aspire higher goal
 - ◆ JANCAE is a NPO and emphasize public benefit

The working group structure

Code usage manner

Each theory of yield functions



Flame work of UMMDp

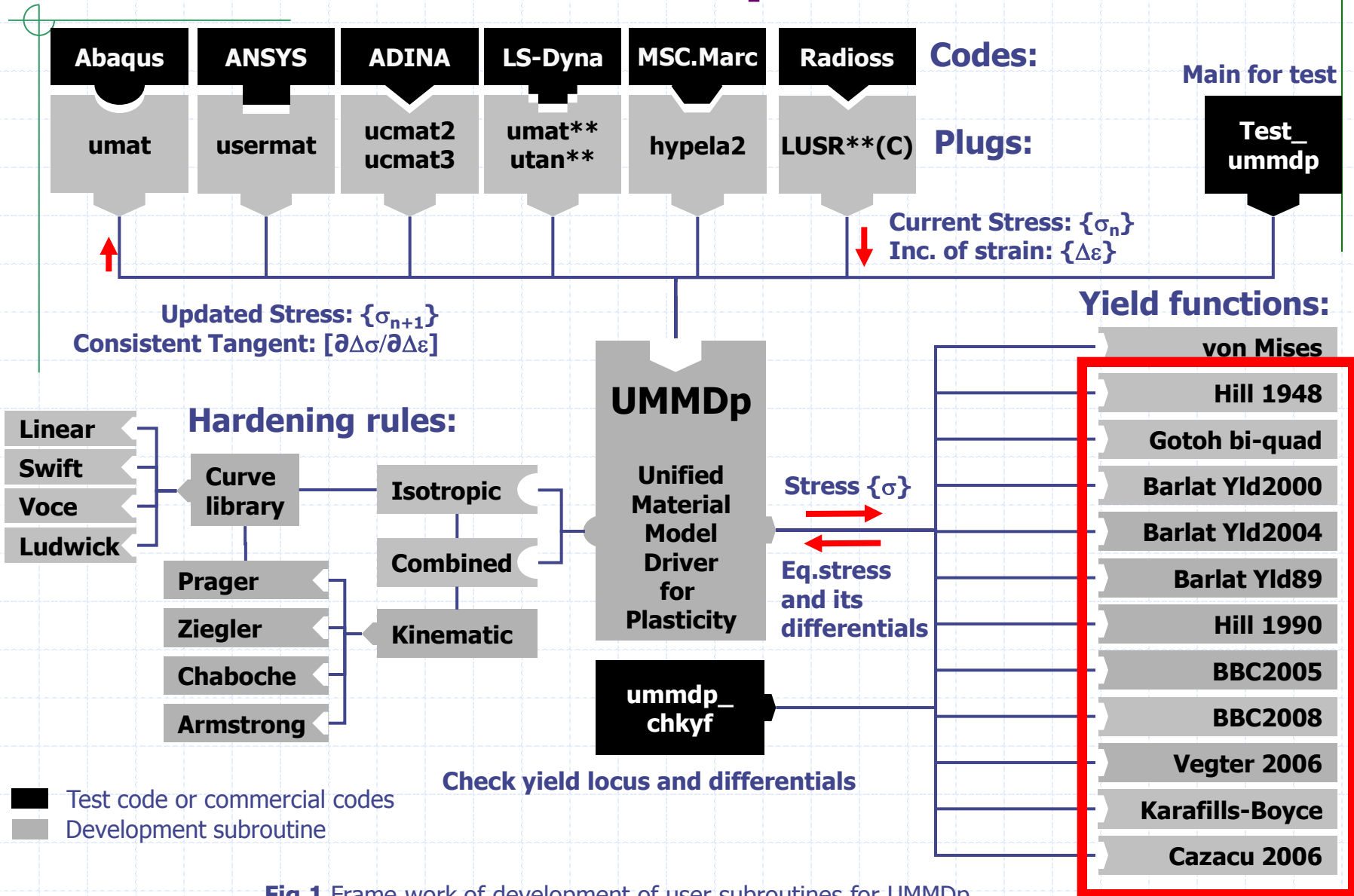
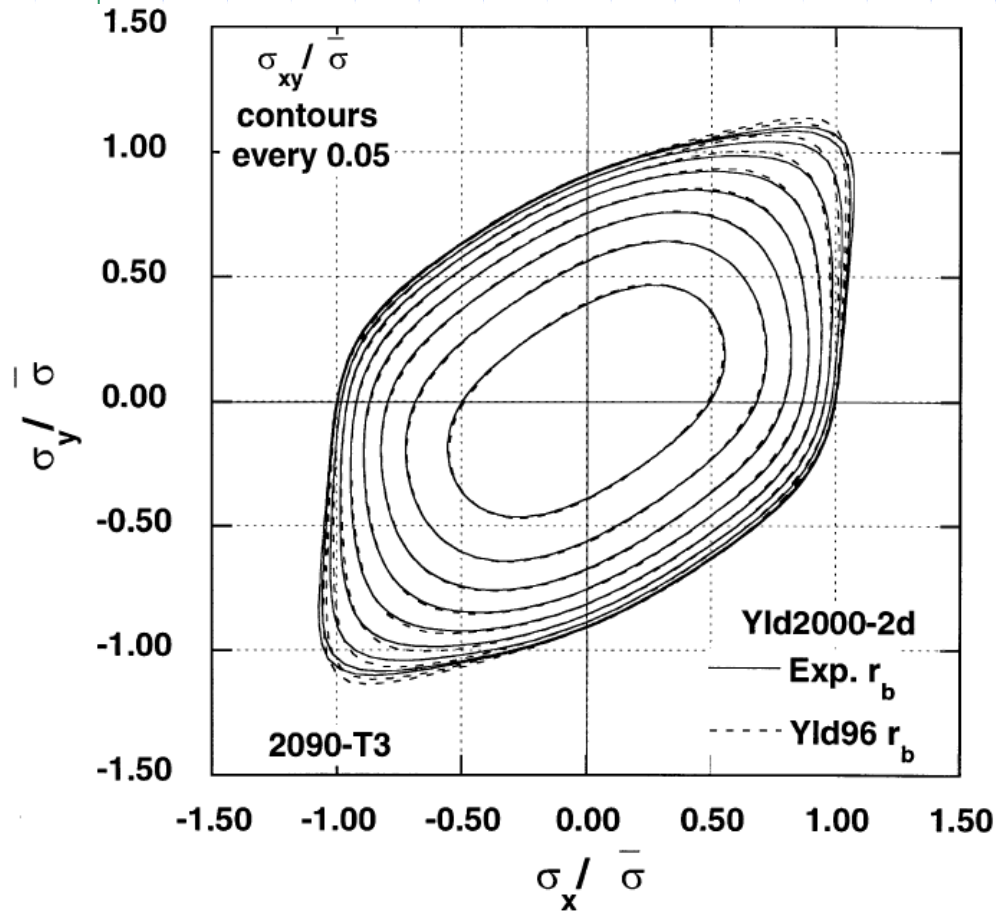


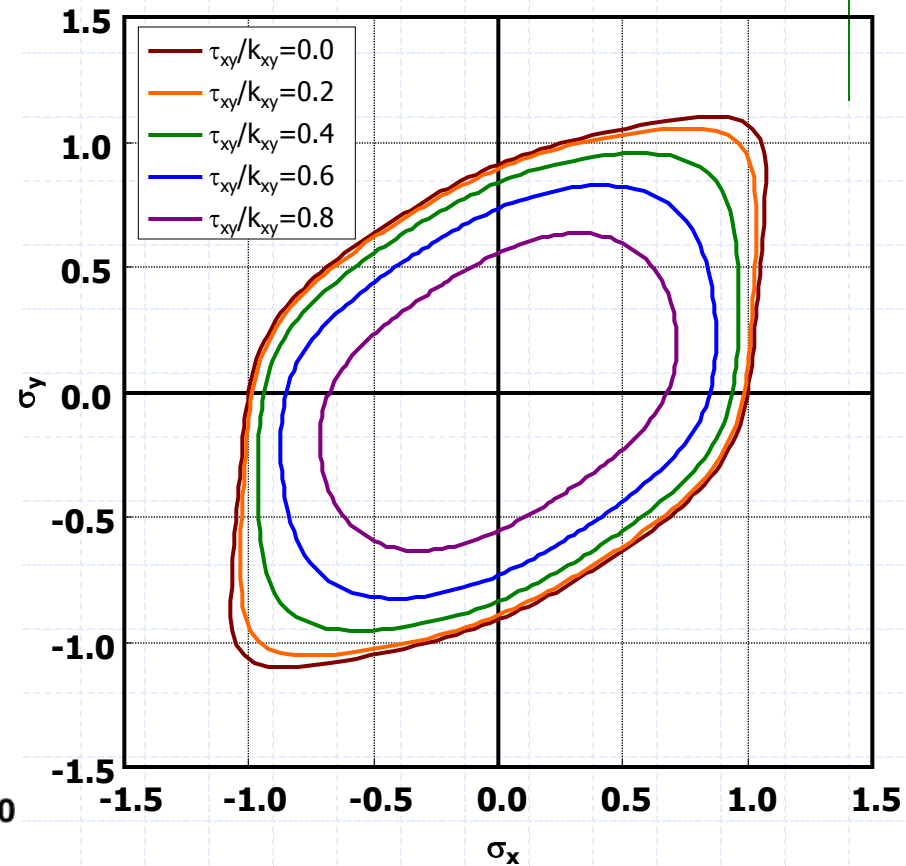
Fig.1 Frame work of development of user subroutines for UMMDp

Yield function : Yld2000

Barlat yld2k paper



Chkyf output xy.txt graph



Users members were in charge

“Yield function subroutines” by Users

- ◆ Program by industrial users
 - Differ from vendor engineers, their understanding level and motivation are different
 - ◆ “I’m a process design engineer of metal forming.”
 - ◆ “I’m not involved in anisotropic, but it’s an good opportunity to study it.”
 - ◆ “I used Fortran for the first time in this project.”
 - ◆ “It is hard to read English papers.”

- ◆ Variety of environment and positions
 - Difficult to obtain understanding from companies
 - ◆ As a result, it was a winter vacation homework as self-development
 - ◆ Positive to open to public

- ◆ Thank you to all users who participates in the project

Flame work of UMMDp

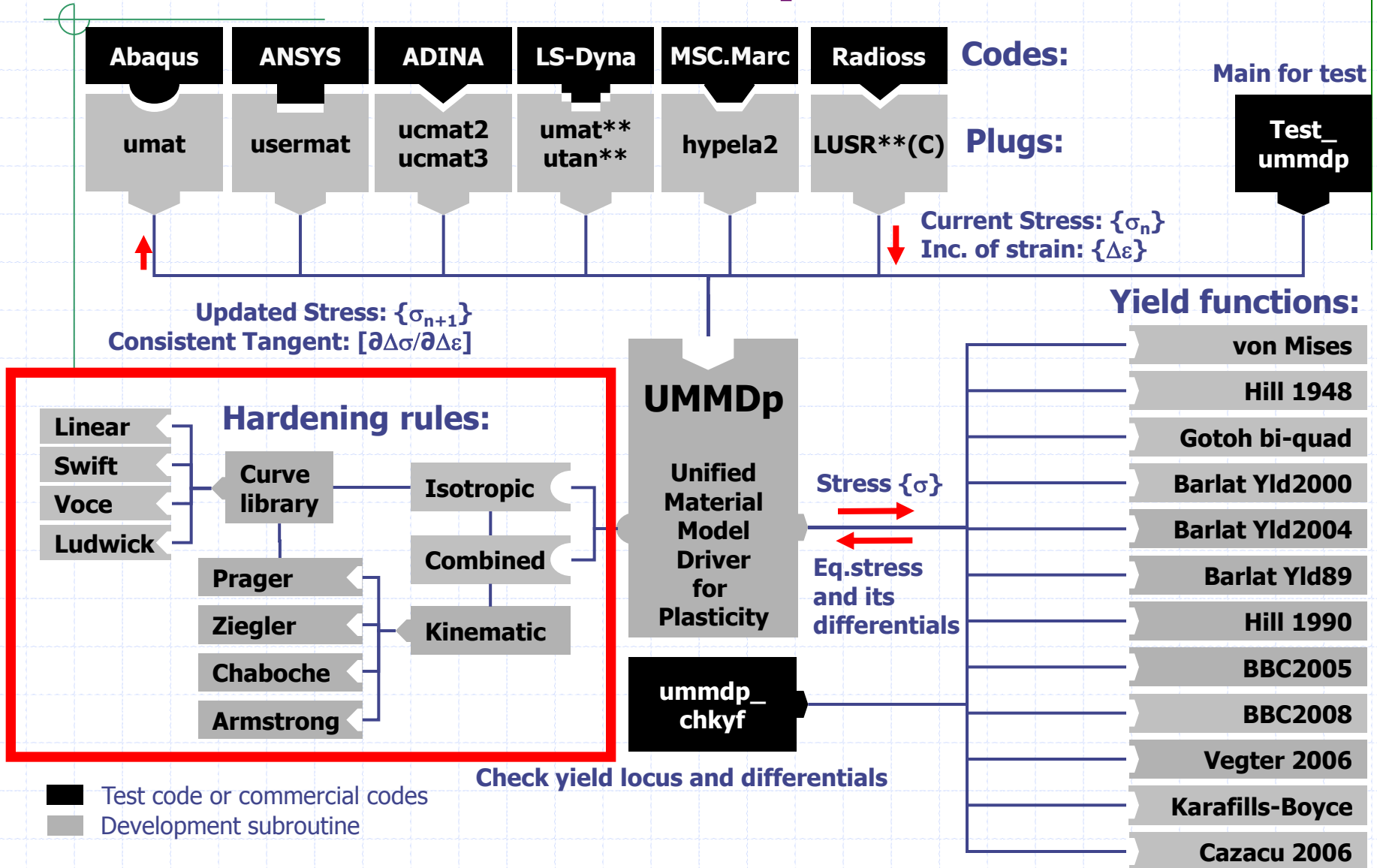
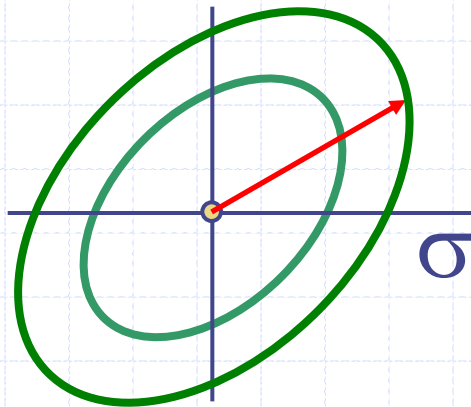


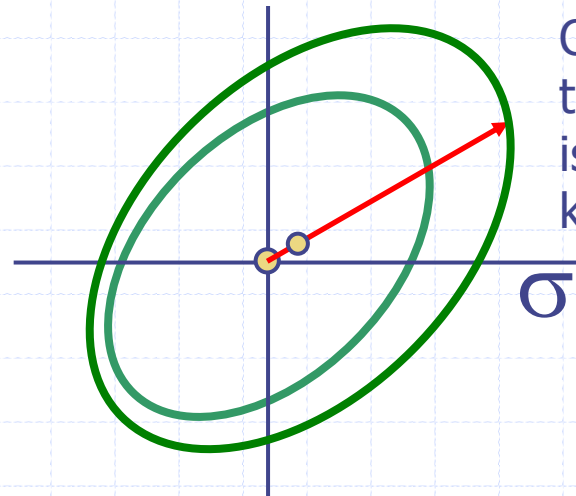
Fig.1 Frame work of development of user subroutines for UMMDp

Hardening law: Combined hardening model

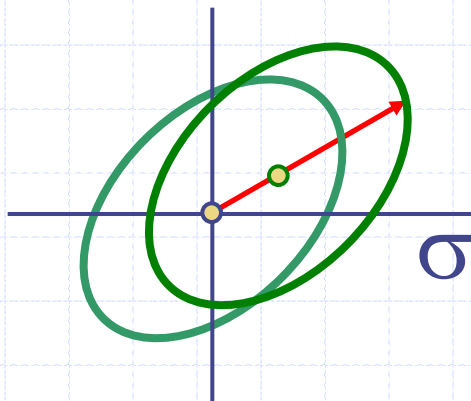
Isotropic hardening



Combined hardening is the superset of isotropic hardening and kinematic hardening.



Kinematic hardening



Combined (Mixed) hardening

Isotropic hardening and kinematic hardening are not exclusive options

Only one of those can not explain natural phenomenon perfectly. In reality, it's correct to consider that these 2 hardening laws are being together.

例:「初期降伏応力の二倍の応力まで引張って除荷(応力をゼロに)した際に、逆降伏が生じなかったため、この金属は移動硬化ではなく、等方硬化である。」という話は一見正しそうに聞こえる。しかし、「完全な移動硬化」でないことを示しているが、「完全な等方硬化」であることの証明にはなっていない。

Basic theory of combined hardening

- ◆ Combined hardening is superset
 - Isotropic hardening and kinematic hardening are not exclusive options
 - Develop the combined hardening
- ◆ Basic equation
 - For user subroutine, Voigt notation is used
 - Use backward Euler is used same as isotropic hardening
 - Explain back stress as $\{X\}$ and use evolution equation of back stress.

Additive Decomposition

$$\{\Delta\varepsilon\} = \{\Delta\varepsilon^p\} + \{\Delta\varepsilon^e\}$$

Hooke's law

$$\{\Delta\sigma\} = [D^e]\{\Delta\varepsilon^e\}$$

Normality rule

$$\{\Delta\varepsilon^p\} = \Delta p \frac{\partial \sigma_e}{\partial \{\sigma_{n+1}\}} = \Delta p \frac{\partial \sigma_e}{\partial \{\sigma_{n+1} - X_{n+1}\}}$$

Yield criterion

$$\sigma_e(\sigma_{n+1}) - \sigma_Y(p_{n+1}) = 0 \quad \sigma_e(\sigma_{n+1} - X_{n+1}) - \sigma_Y(p_{n+1}) = 0$$

Eq. of evolution of X

$$\{\Delta X\} = \Delta p \{V(\sigma_{n+1}, X_{n+1}, p_{n+1})\}$$

Kinematic hardening model

◆ Classic back stress model

Eq. of evolution of Back stress
General Form $\{\Delta X\} = \Delta p \{V(\sigma, X, p)\}$

- W.Prager

$$\{\Delta X\} = c(p) \{\Delta \varepsilon^p\}$$

$$\Rightarrow \{V\} = c(p) \frac{\partial \sigma_e}{\partial \{\eta\}} = c(p) \{m\}$$

- H.Ziegler

$$\{\Delta X\} = c(p) \Delta p \{ \{\sigma'\} - \{X\} \}$$

$$\Rightarrow \{V\} = c(p) \{ \{\sigma'\} - \{X\} \}$$

- P.J.Armstrong-C.O.Frederick

$$\{\Delta X\} = c(p) \{\Delta \varepsilon^p\} - \Delta p \gamma(p) \{X\}$$

$$\Rightarrow \{V\} = c(p) \{m\} - \gamma(p) \{X\}$$

Increment of equivalent plastic strain (or plastic multiplier) can be calculated from increment of plastic strain, when using normality rule

$$\{\Delta \varepsilon^p\} = \Delta p \frac{\partial \sigma_e}{\partial \{\sigma - X\}}$$

Δp is included in the equation in some way, considering that back stress evolves in association with progress of plastic deformation

Basic theory of combined hardening

◆ Stress integration

Variables : $\sigma_{n+1}, X_{n+1}, \Delta p$

Constant : $\Delta \varepsilon, p_n, \sigma_n, X_n$

$$\{m_{n+1}\} = \frac{\partial \sigma_e}{\partial \{\sigma - X\}} \Big|_{n+1}$$

$$\{\sigma^{Try}\} \equiv \{\sigma_n\} + [D^e] \{\Delta \varepsilon\}$$

Yield criterion

$$\sigma_e(\sigma_{n+1} - X_{n+1}) - \sigma_Y(p_{n+1}) = \sigma_e(\sigma_{n+1} - X_{n+1}) - \sigma_Y(p_n + \Delta p) = 0$$

Updated stress

$$\{\sigma_{n+1}\} = \{\sigma_n\} + \{\Delta \sigma\} = \{\sigma_n\} + [D^e] \{\Delta \varepsilon\} - [D^e] \Delta p \frac{\partial \sigma_e}{\partial \{\sigma - X\}} \Big|_{n+1} \equiv \{\sigma^{Try}\} - \Delta p [D^e] \{m_{n+1}\}$$

Elastro-plastic additive decomposition, Hooke law

Simplification

Back stress

$$\{X_{n+1}\} = \{X_n\} + \{\Delta X\}$$

$$\{\Delta X\} = \Delta p \{v\} = \Delta p \{V(\sigma_{n+1}, X_{n+1}, p + \Delta p)\} \quad \text{Back stress evolution equation}$$

All those equations must be satisfied. Define following “g” as the error functions

$$g_1 = \sigma_e(\sigma_{n+1} - X_{n+1}) - \sigma_Y(p_n + \Delta p) \quad \rightarrow \quad \mathbf{0} \quad \text{Scalar equation}$$

$$\{g_2\} = \{\sigma_{n+1}\} - \{\sigma^{Try}\} + \Delta p [D^e] \{m_{n+1}\} \quad \rightarrow \quad \{\mathbf{0}\} \quad \text{Vector equation}$$

$$\{g_3\} = \{X_{n+1}\} - \{X_n\} - \Delta p \{V(\sigma_{n+1}, X_{n+1}, p + \Delta p)\} \quad \rightarrow \quad \{\mathbf{0}\} \quad \text{Vector equation}$$

2n+1
simultaneous
non-linear
equation

Basic theory of combined hardening

Summary of stress integration

Assumption of the default value (not yielding)

Start

$$\Delta p_{(0)} = 0 \quad \mathbf{i=0}$$

$$\{\sigma_{(0)}\} = \{\sigma^{Try}\}$$

$$\{X_{(0)}\} = \{X_n\}$$

$$\sigma_e(\sigma_{(0)} - X_{(0)}) > \sigma_Y(p_n + 0)$$

Calculation of intermediate variables

$$\begin{Bmatrix} \{b_{sp(i)}\} \\ \{b_{xp(i)}\} \end{Bmatrix} = [A]^{-1} \begin{Bmatrix} -[D^e]\{m_{(i)}\} \\ \{V_{(i)}\} + \Delta p_{(i)} \frac{\partial \{V\}}{\partial p} \end{Bmatrix}$$

$$\begin{Bmatrix} \{b_{s0(i)}\} \\ \{b_{x0(i)}\} \end{Bmatrix} = [A]^{-1} \begin{Bmatrix} -\{g_{2(i)}\} \\ -\{g_{3(i)}\} \end{Bmatrix}$$

$$[N_{(i)}] = \frac{\partial \sigma_e}{\partial \{\sigma - X\} \partial \{\sigma - X\}^T} \Big|_{(i)}$$

$$\{m_{(i)}\} = \frac{\partial \sigma_e}{\partial \{\sigma - X\}} \Big|_{(i)}$$

$$[\mathbb{I}] + \Delta p_{(i)} [D] \frac{\partial \{V\}}{\partial p} \Big|_{(i)} \quad [\mathbb{I}] - \Delta p_{(i)} \frac{\partial \{V\}}{\partial \{X\}^T} \Big|_{(i)}$$

Calculating $\delta\Delta p$ (correction amount of Δp)

$$\delta\Delta p = \frac{g_{1(i)} + \{m_{(i)}\}^T \left\{ \{b_{s0(i)}\} - \{b_{x0(i)}\} \right\}}{\frac{\partial \sigma_Y}{\partial p} \Big|_{(i)} \delta\Delta p - \{m_{(i)}\}^T \left\{ \{b_{sp(i)}\} - \{b_{xp(i)}\} \right\}}$$

Calculating $\{\delta\sigma\}$ and $\{\delta X\}$
(correction amount of $\{\sigma\}$ and $\{X\}$)

$$\begin{Bmatrix} \{\delta\sigma\} \\ \{\delta X\} \end{Bmatrix} = \begin{Bmatrix} \{b_{s0(i)}\} \\ \{b_{x0(i)}\} \end{Bmatrix} + \delta\Delta p \begin{Bmatrix} \{b_{sp(i)}\} \\ \{b_{xp(i)}\} \end{Bmatrix}$$

Update

$i=i+1$

$$\Delta p_{(i+1)} = \Delta p_{(i)} + \delta\Delta p$$

$$\{\sigma_{(i+1)}\} = \{\sigma_{(i)}\} + \{\delta\sigma\}$$

$$\{X_{(i+1)}\} = \{X_{(i)}\} + \{\delta X\}$$

**Newton
Raphson
Iteration**

If error function is small enough?

No

$$g_1 \approx 0$$

$$\{g_2\} \approx \{0\}$$

$$\{g_3\} \approx \{0\}$$

Yes

End of stress integration

End

Flame work of UMMDp

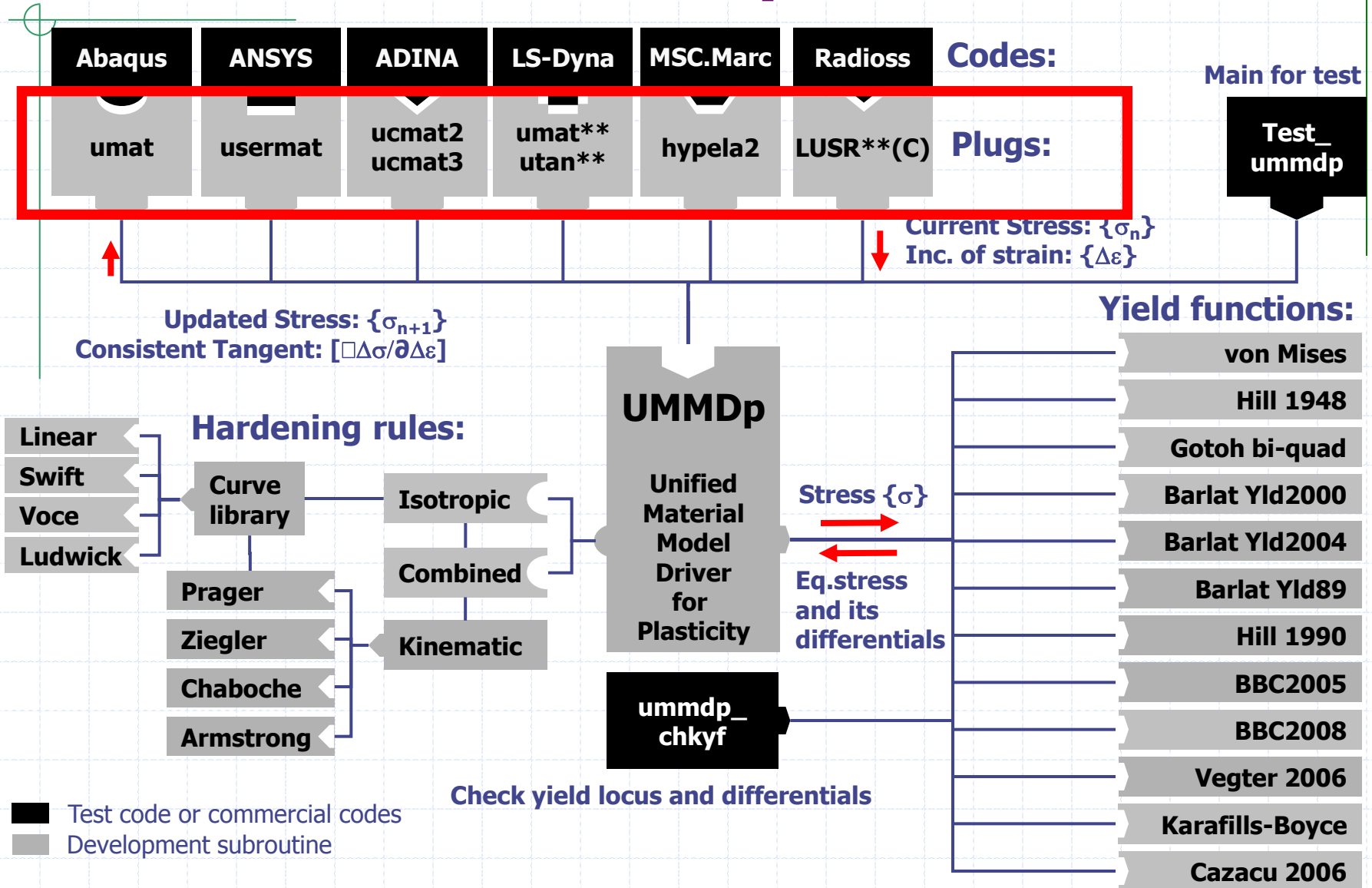


Fig.1 Frame work of development of user subroutines for UMMDp

Commercial codes

Although there are differences of variable names and storing ways, basically they have similar frameworks.

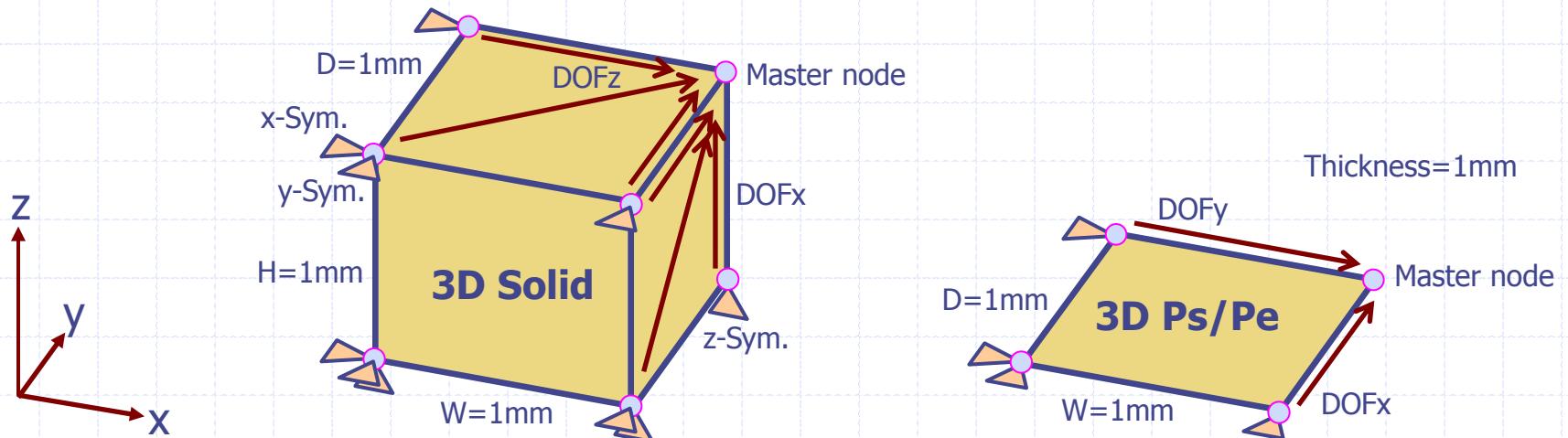
Code	Marc	Abaqus	ANSYS	LS-DYNA	ADINA	UMMDp
UsrSubR	hypela2	umat	usermat	Umat/utan	ucmat2 ucmat3	jancae_plasticity
Stress component	S	STRESS	stress	sig	stress	s1,s2
Strain increment	DE	DSTRAN	dStrain	eps	deps	de
consistent tangent modulus matrix	D	DDSDDE	dsdePI	Es	d	ddsdde
Stress component number	NGENS, NDI, NSHEAR	NTENS, NDI, NSHR	ncomp, nDirect, nShear	eltype で判断	固定 (ucmat2/ 3で判断)	nttl, nnrm, nshr
State variable(histor y variable)	T,DT	STATEV	ustatev	Hsv	ARRAY	p,dp,x(10,nttl)
Number of state variable	NSTATS	NSTATEV	nStatev	NHV	LGTH1	
End SubR	QUIT	XIT	EXIT	adios	END _(KEY=4)	jancae_exit

Volunteers from software vendors checked the software own manners.

Verification Test Problems

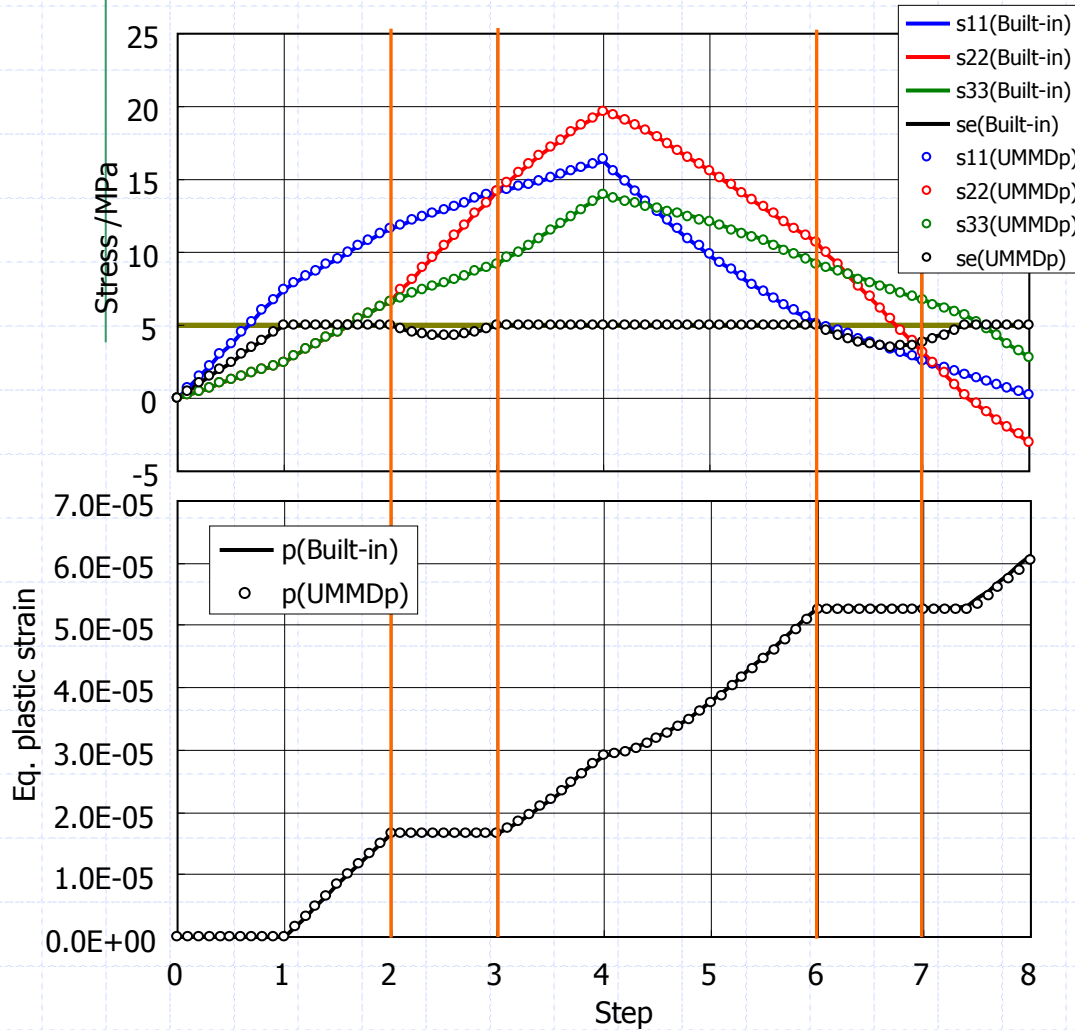
- ◆ **VT01** : Plane Strain/Disp. Control/Perfect Plasticity
- ◆ **VT02** : Plane Strain/Disp. Control/Strain Hardening
- ◆ **VT03** : Plane Stress/Disp. Control/Perfect Plasticity
- ◆ **VT04** : 3D Solid/Disp. Control/Strain Hardening
- ◆ **VT05** : 3D Solid/Force Control/Strain Hardening
- ◆ **VT06** : Plane Strain/Disp. Control/Strain Hardening (Simple Shear)

	Plane Strain	Plane Stress	3D Solid
Perfect Plasticity	VT01(Disp.)	VT03(Disp.)	--
Strain Hardening	VT02(Disp.) VT06(Shear)	--	VT04(Disp.) VT05(Force)

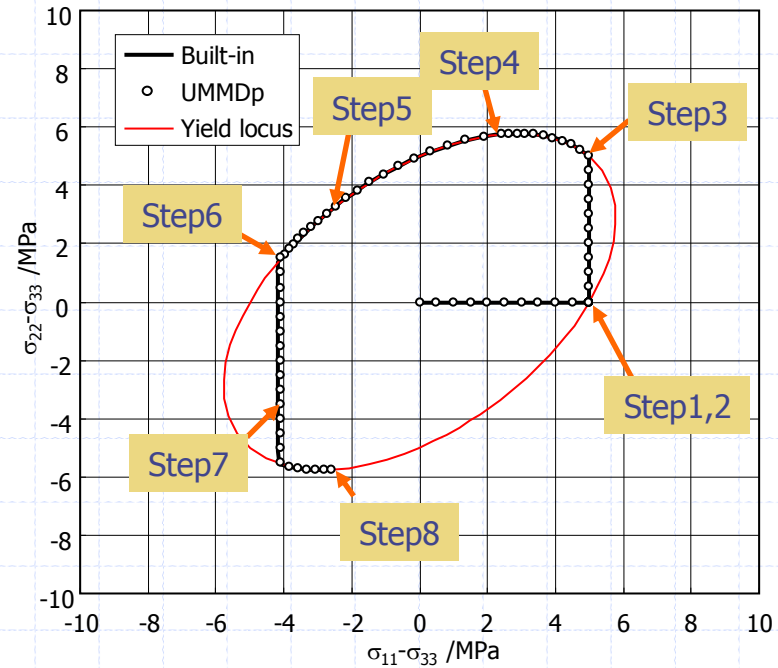


Plug for MSC.Marc

Marc



Line : Built in von Mises
Plot : UMMDp

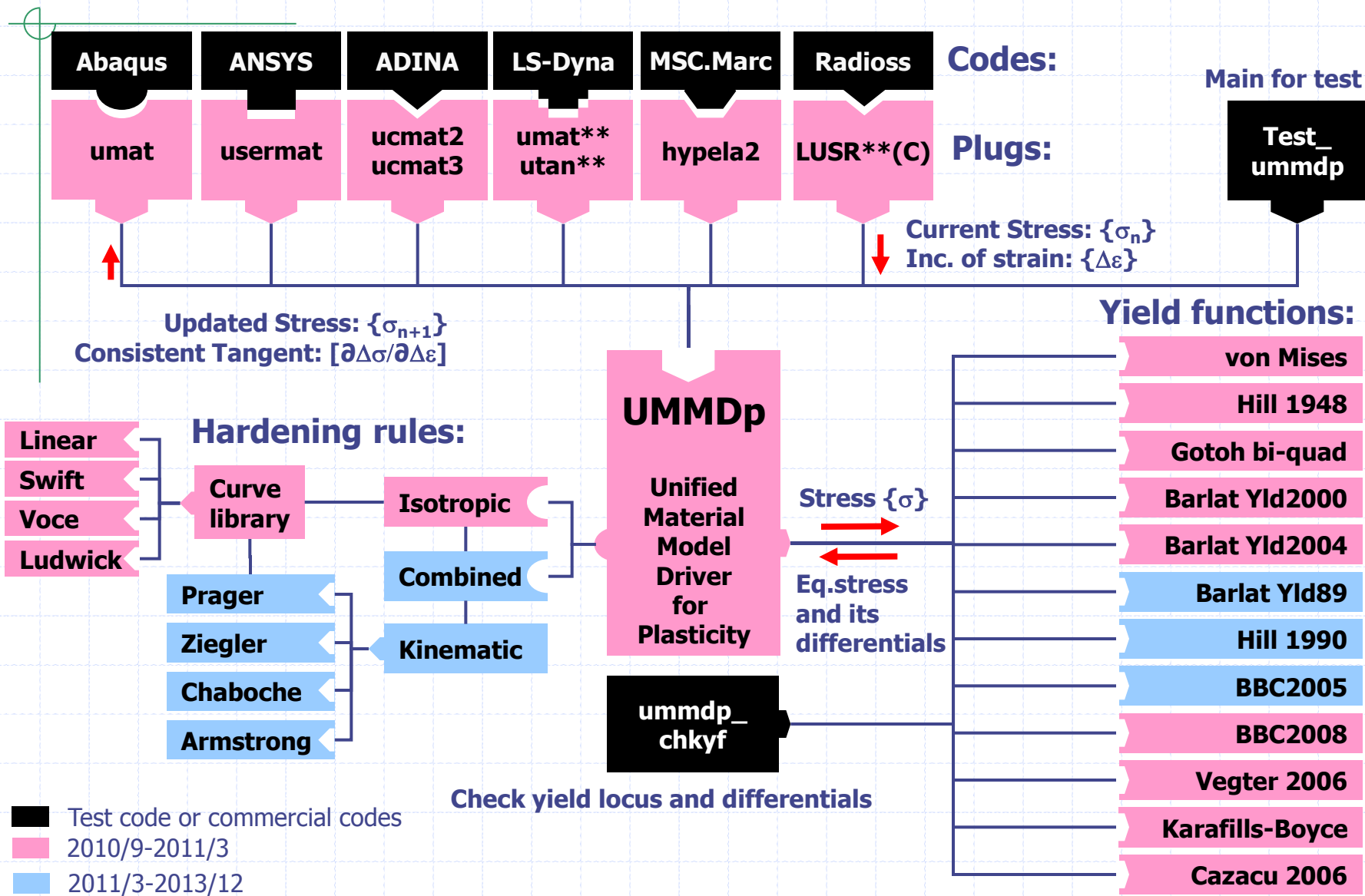


“Plugs” by Professionals.

◆ Engineers from vendors

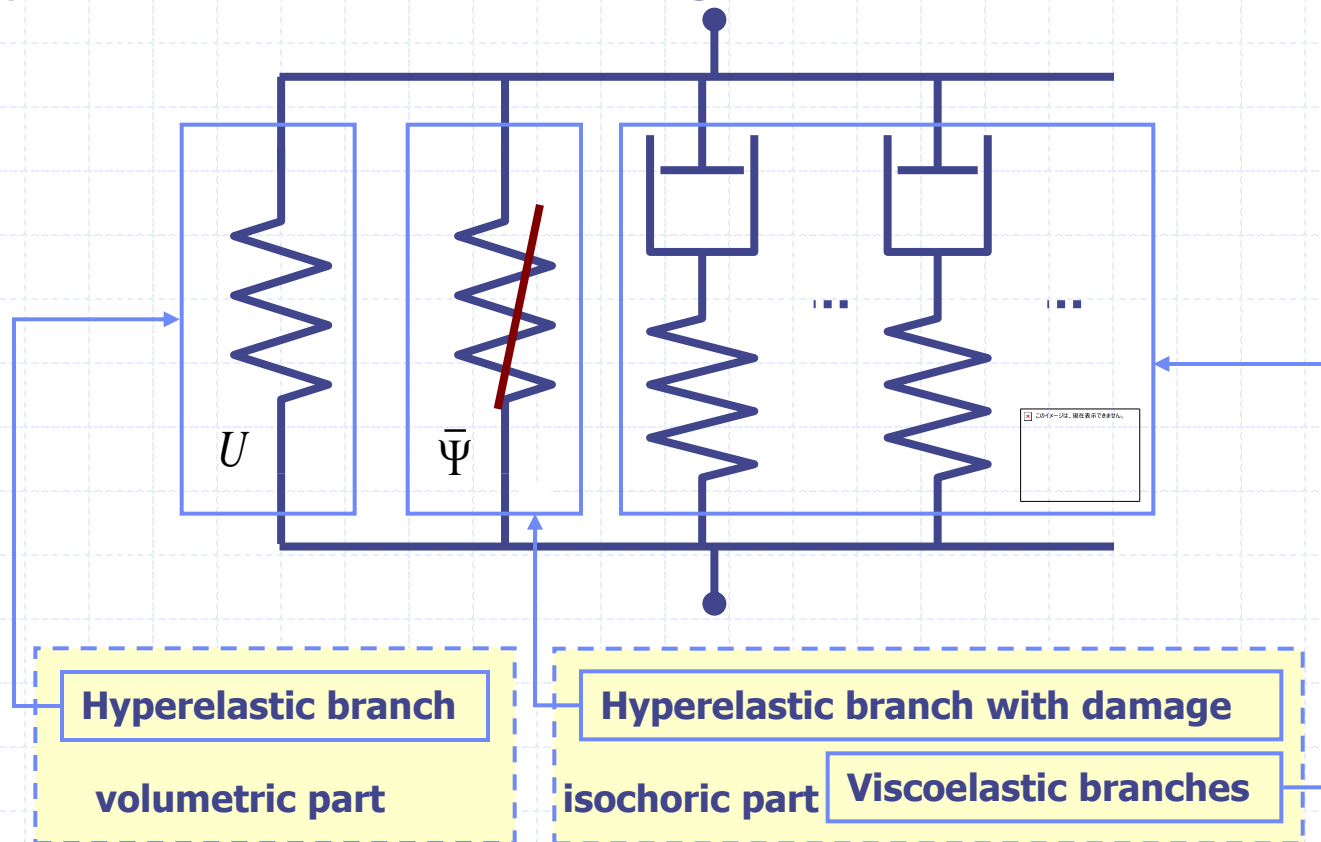
- It was valuable to gain vendors engineers participation
 - ◆ **It's worthy to see codes by professionals.**
- Words from vendor engineers
 - ◆ As user subroutine is basically an exempt of user support, we don't have an opportunity to be involved in it positively. As a result we are not necessarily understand it enough.
 - ◆ **We could establish a good relationship as numerical analysis engineers which is different from the contract based relationship.**
- Thanks for participation
 - ◆ Participation as volunteer or self development by paying
- What supported the motivation of vendors engineers was the effort of industrial users.

Flame work



Development goes on

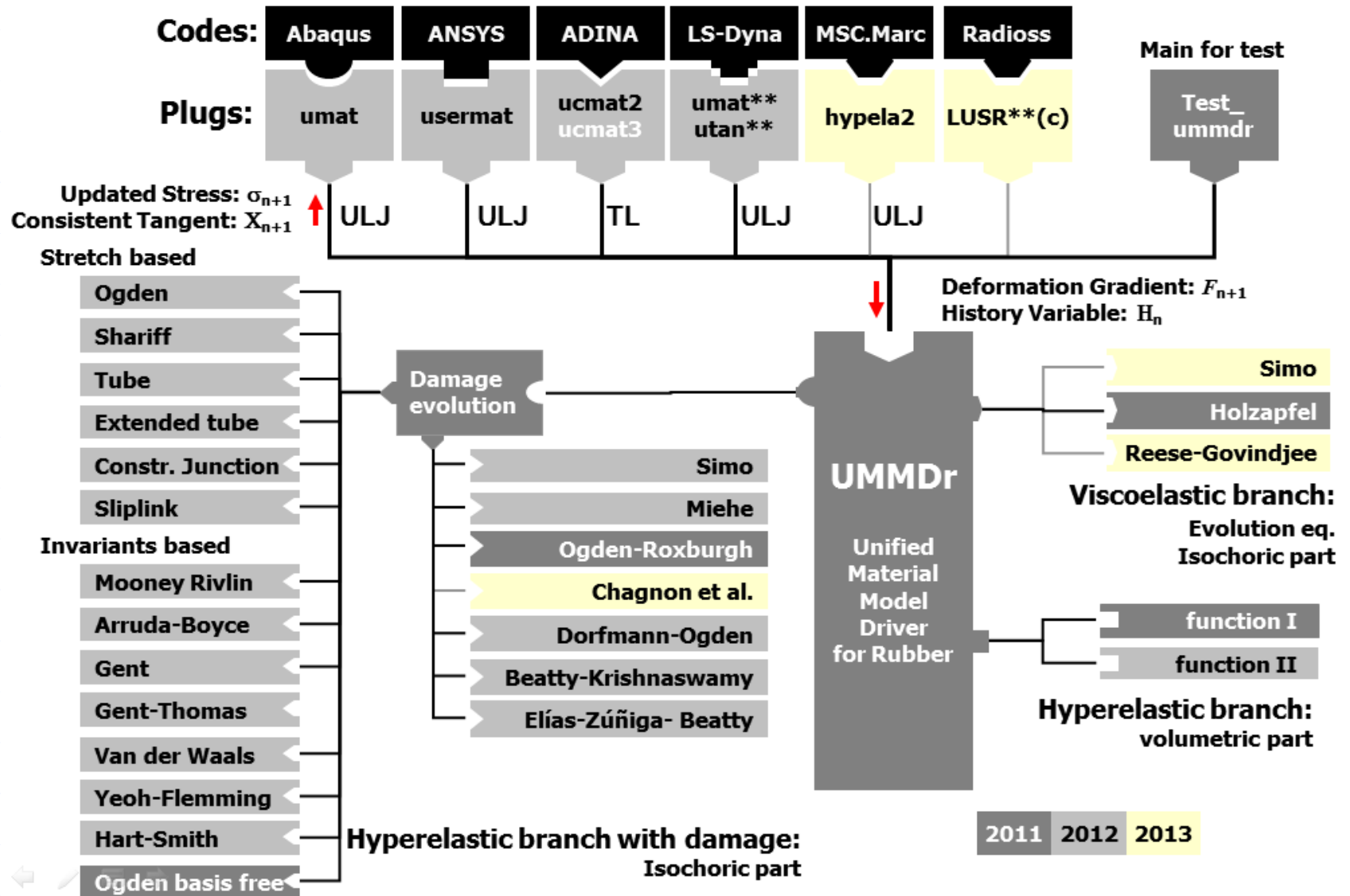
- ◆ Hyperelastic, viscoelastic, damage framework of constitutive law



$$\Psi(C, h, q_1, \dots, q_n) = \underbrace{U(J)}_{\text{volumetric part}} + \underbrace{\bar{\Psi}(\bar{C}, h)}_{\text{equilibrium part with damage}} + \underbrace{\bar{\Psi}_{\text{NEQ}}(\bar{C}, q_1, \dots, q_n)}_{\text{non-equilibrium part}}$$

isochoric part

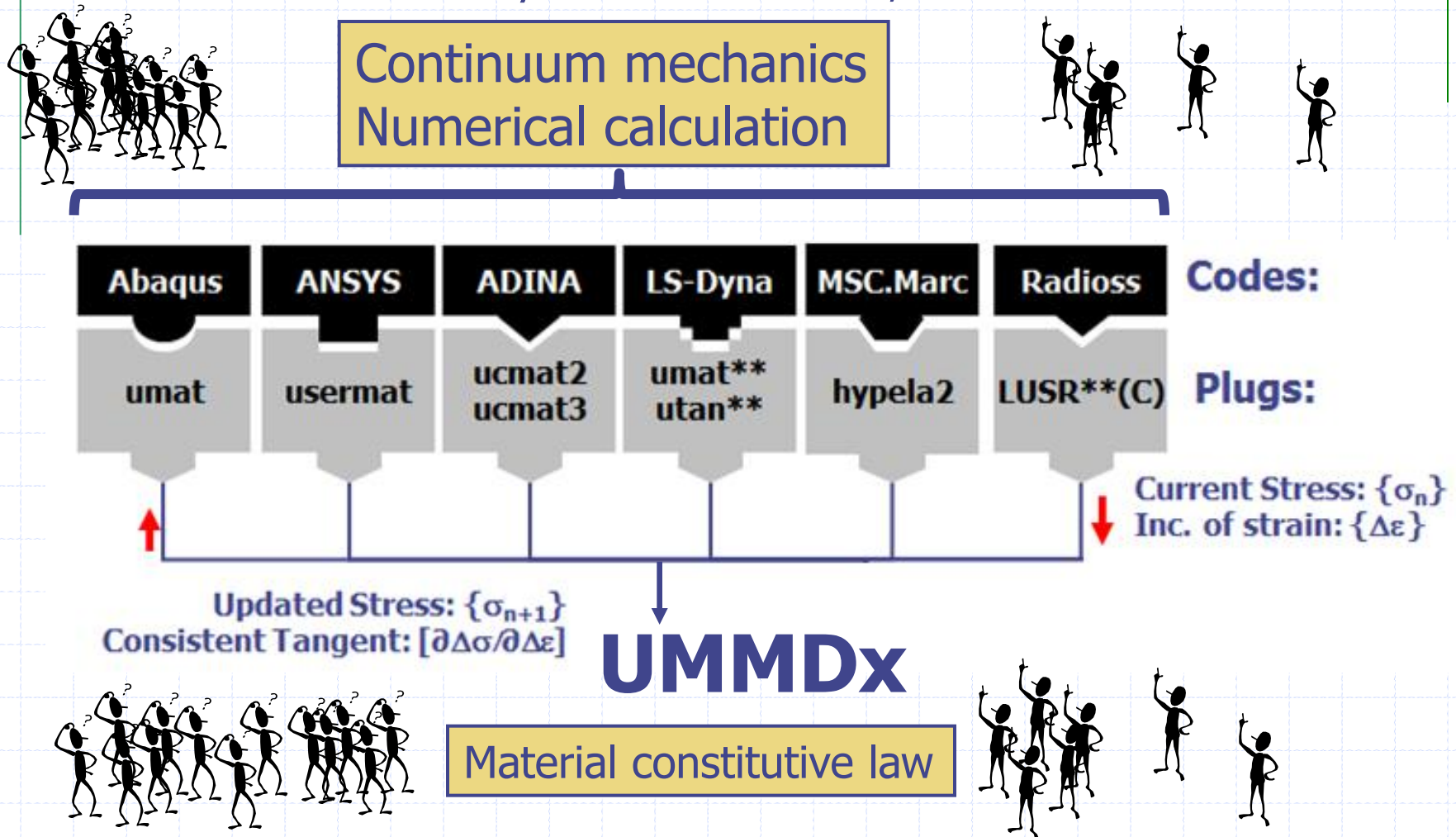
Development goes on



Summary(1) NPO

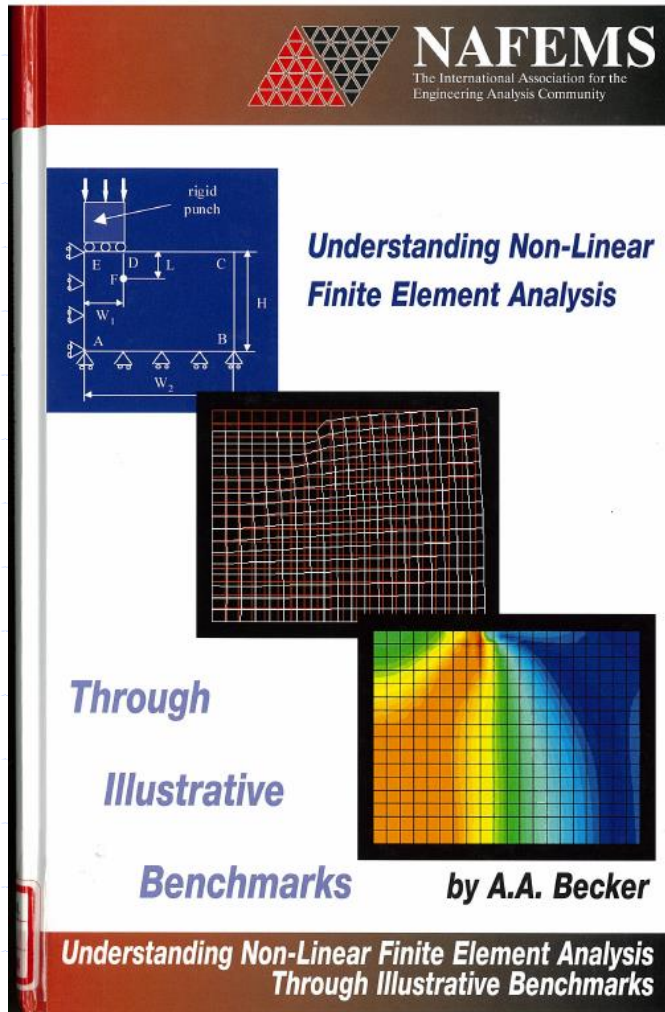
◆ Approach as NPO

- Activities that only NPO can work on, not societies not vendors



Summary(2) NAFEMS

Verification (Benchmark)



2.4 FUNDAMENTAL 2D PLASTICITY BENCHMARK

2.4.1 Physical Attributes

This problem consists of a simple 2D geometry subjected to prescribed displacements in order to demonstrate several aspects of plastic behaviour including the following:

- Biaxial yielding
- Perfect plasticity
- Isotropic hardening
- Plastic flow
- Unloading and subsequent reloading
- Residual stresses after unloading
- Prescribed displacements at all nodes (displacement-control)

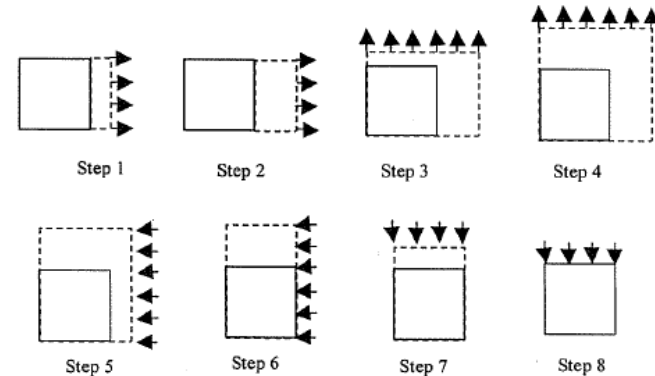
2.4.2 Problem Definition

A square plate is stretched in the x- and y-directions and then returned to its original shape. The plate is assumed sufficiently thick in the z-direction for plane strain conditions to be applicable.

The prescribed displacements are applied in 8 steps, as follows (see Figure 2.11):

- Stretching in the x-direction until the plate just yields, followed by further stretching in the x-direction causing plastic flow, i.e. post-yield behaviour.
- Stretching in the y-direction in two steps.
- Compression in the x-direction in two steps.
- Compression in the y-direction in two steps.

At the end of the final load step, the plate is returned to its original dimensions.



Summary

- ◆ Situation in Japan:
 - We are mainly using commercial CAE codes developed in other countries.
 - We focus on the applications using commercial codes.

- ◆ Convenient tools are welcome
 - The purpose of refrigerator is to keep cool.
 - The purpose of vehicle is to move safely.
 - The purpose of word processor is to layout document.
 - ◆ However word processor doesn't make text. The important of text is the what it says.

- ◆ Same for CAE. We can't use CAE without deep understanding
 - What kind of model we make for the specific problem.
 - What we understand from the result.
 - We still can't make model which perfectly recreate the "real".

Summary

◆ NAFEMS : Classic Documents

- There are records of the verification for each commercial code
- Suggesting process to accumulate our understanding not to use simulation without any consideration

◆ Where and how we should start

- We can use sophisticated commercial codes if having enough budget.
- Can we use CAE without classic records?
- NAFEMS classic documents would be a compass of verification process for us.

◆ V&V : recommendation of Verification

- Don't we think that Verification is software vendors role and Validation is users role?
- Validation is necessary as the common language in companies.
"quantity"
- Verification is necessary to accumulate our understanding. **"quality"**